

矩阵、向量求导法则

(1) 行向量对元素求导

设 $\mathbf{y}^T = [y_1 \ \cdots \ y_n]$ 是 n 维行向量, x 是元素, 则 $\frac{\partial \mathbf{y}^T}{\partial x} = \left[\frac{\partial y_1}{\partial x} \ \cdots \ \frac{\partial y_n}{\partial x} \right]$ 。

(2) 列向量对元素求导

设 $\mathbf{y} = \begin{bmatrix} y_1 \\ \vdots \\ y_m \end{bmatrix}$ 是 m 维列向量, x 是元素, 则 $\frac{\partial \mathbf{y}}{\partial x} = \begin{bmatrix} \frac{\partial y_1}{\partial x} \\ \vdots \\ \frac{\partial y_m}{\partial x} \end{bmatrix}$ 。

(3) 矩阵对元素求导

设 $Y = \begin{bmatrix} y_{11} & \cdots & y_{1n} \\ \vdots & & \vdots \\ y_{m1} & \cdots & y_{mn} \end{bmatrix}$ 是 $m \times n$ 矩阵, x 是元素, 则

$$\frac{\partial Y}{\partial x} = \begin{bmatrix} \frac{\partial y_{11}}{\partial x} & \cdots & \frac{\partial y_{1n}}{\partial x} \\ \vdots & & \vdots \\ \frac{\partial y_{m1}}{\partial x} & \cdots & \frac{\partial y_{mn}}{\partial x} \end{bmatrix}。$$

(4) 元素对行向量求导

设 y 是元素, $\mathbf{x}^T = [x_1 \ \cdots \ x_q]$ 是 q 维行向量, 则 $\frac{\partial y}{\partial \mathbf{x}^T} = \left[\frac{\partial y}{\partial x_1} \ \cdots \ \frac{\partial y}{\partial x_q} \right]$ 。

(5) 元素对列向量求导

设 y 是元素, $\mathbf{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_p \end{bmatrix}$ 是 p 维列向量, 则 $\frac{\partial y}{\partial \mathbf{x}} = \begin{bmatrix} \frac{\partial y}{\partial x_1} \\ \vdots \\ \frac{\partial y}{\partial x_p} \end{bmatrix}$ 。

(6) 元素对矩阵求导

设 y 是元素, $X = \begin{bmatrix} x_{11} & \cdots & x_{1q} \\ \vdots & & \vdots \\ x_{p1} & \cdots & x_{pq} \end{bmatrix}$ 是 $p \times q$ 矩阵, 则

$$\frac{\partial y}{\partial X} = \begin{bmatrix} \frac{\partial y}{\partial x_{11}} & \cdots & \frac{\partial y}{\partial x_{1q}} \\ \vdots & & \vdots \\ \frac{\partial y}{\partial x_{p1}} & \cdots & \frac{\partial y}{\partial x_{pq}} \end{bmatrix}。$$

(7) 行向量对列向量求导

设 $\mathbf{y}^T = [y_1 \ \cdots \ y_n]$ 是 n 维行向量, $\mathbf{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_p \end{bmatrix}$ 是 p 维列向量, 则

$$\frac{\partial \mathbf{y}^T}{\partial \mathbf{x}} = \begin{bmatrix} \frac{\partial y_1}{\partial x_1} & \cdots & \frac{\partial y_n}{\partial x_1} \\ \vdots & & \vdots \\ \frac{\partial y_1}{\partial x_p} & \cdots & \frac{\partial y_n}{\partial x_p} \end{bmatrix}。$$

(8) 列向量对行向量求导

设 $\mathbf{y} = \begin{bmatrix} y_1 \\ \vdots \\ y_m \end{bmatrix}$ 是 m 维列向量, $\mathbf{x}^T = [x_1 \ \cdots \ x_q]$ 是 q 维行向量, 则

$$\frac{\partial \mathbf{y}}{\partial \mathbf{x}^T} = \begin{bmatrix} \frac{\partial y_1}{\partial x_1} & \cdots & \frac{\partial y_1}{\partial x_q} \\ \vdots & & \vdots \\ \frac{\partial y_m}{\partial x_1} & \cdots & \frac{\partial y_m}{\partial x_q} \end{bmatrix}。$$

(9) 行向量对行向量求导

设 $\mathbf{y}^T = [y_1 \ \cdots \ y_n]$ 是 n 维行向量, $\mathbf{x}^T = [x_1 \ \cdots \ x_q]$ 是 q 维行向量, 则

$$\frac{\partial \mathbf{y}^T}{\partial \mathbf{x}^T} = \left[\frac{\partial \mathbf{y}^T}{\partial x_1} \ \cdots \ \frac{\partial \mathbf{y}^T}{\partial x_q} \right]。$$

(10) 列向量对列向量求导

设 $\mathbf{y} = \begin{bmatrix} y_1 \\ \vdots \\ y_m \end{bmatrix}$ 是 m 维列向量, $\mathbf{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_p \end{bmatrix}$ 是 p 维列向量, 则 $\frac{\partial \mathbf{y}}{\partial \mathbf{x}} = \begin{bmatrix} \frac{\partial y_1}{\partial \mathbf{x}} \\ \vdots \\ \frac{\partial y_m}{\partial \mathbf{x}} \end{bmatrix}。$

(11) 矩阵对行向量求导

设 $Y = \begin{bmatrix} y_{11} & \cdots & y_{1n} \\ \vdots & & \vdots \\ y_{m1} & \cdots & y_{mn} \end{bmatrix}$ 是 $m \times n$ 矩阵, $\mathbf{x}^T = [x_1 \ \cdots \ x_q]$ 是 q 维行向量, 则

$$\frac{\partial Y}{\partial \mathbf{x}^T} = \left[\frac{\partial Y}{\partial x_1} \quad \cdots \quad \frac{\partial Y}{\partial x_q} \right]。$$

(12) 矩阵对列向量求导

设 $Y = \begin{bmatrix} y_{11} & \cdots & y_{1n} \\ \vdots & & \vdots \\ y_{m1} & \cdots & y_{mn} \end{bmatrix}$ 是 $m \times n$ 矩阵, $\mathbf{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_p \end{bmatrix}$ 是 p 维列向量, 则

$$\frac{\partial Y}{\partial \mathbf{x}} = \begin{bmatrix} \frac{\partial y_{11}}{\partial \mathbf{x}} & \cdots & \frac{\partial y_{1n}}{\partial \mathbf{x}} \\ \vdots & & \vdots \\ \frac{\partial y_{m1}}{\partial \mathbf{x}} & \cdots & \frac{\partial y_{mn}}{\partial \mathbf{x}} \end{bmatrix}。$$

(13) 行向量对矩阵求导

设 $\mathbf{y}^T = [y_1 \quad \cdots \quad y_n]$ 是 n 维行向量, $X = \begin{bmatrix} x_{11} & \cdots & x_{1q} \\ \vdots & & \vdots \\ x_{p1} & \cdots & x_{pq} \end{bmatrix}$ 是 $p \times q$ 矩阵, 则

$$\frac{\partial \mathbf{y}^T}{\partial X} = \begin{bmatrix} \frac{\partial \mathbf{y}^T}{\partial x_{11}} & \cdots & \frac{\partial \mathbf{y}^T}{\partial x_{1q}} \\ \vdots & & \vdots \\ \frac{\partial \mathbf{y}^T}{\partial x_{p1}} & \cdots & \frac{\partial \mathbf{y}^T}{\partial x_{pq}} \end{bmatrix}。$$

(14) 列向量对矩阵求导

设 $\mathbf{y} = \begin{bmatrix} y_1 \\ \vdots \\ y_m \end{bmatrix}$ 是 m 维列向量, $X = \begin{bmatrix} x_{11} & \cdots & x_{1q} \\ \vdots & & \vdots \\ x_{p1} & \cdots & x_{pq} \end{bmatrix}$ 是 $p \times q$ 矩阵, 则

$$\frac{\partial \mathbf{y}}{\partial X} = \begin{bmatrix} \frac{\partial y_1}{\partial X} \\ \vdots \\ \frac{\partial y_m}{\partial X} \end{bmatrix}。$$

(15) 矩阵对矩阵求导

设 $Y = \begin{bmatrix} y_{11} & \cdots & y_{1n} \\ \vdots & & \vdots \\ y_{m1} & \cdots & y_{mn} \end{bmatrix} = \begin{bmatrix} \mathbf{y}_1^T \\ \vdots \\ \mathbf{y}_m^T \end{bmatrix}$ 是 $m \times n$ 矩阵, $X = \begin{bmatrix} x_{11} & \cdots & x_{1q} \\ \vdots & & \vdots \\ x_{p1} & \cdots & x_{pq} \end{bmatrix}$

$= [\mathbf{x}_1 \quad \cdots \quad \mathbf{x}_q]$ 是 $p \times q$ 矩阵, 则

$$\frac{\partial Y}{\partial X} = \left[\frac{\partial Y}{\partial \mathbf{x}_1} \quad \dots \quad \frac{\partial Y}{\partial \mathbf{x}_q} \right] = \begin{bmatrix} \frac{\partial \mathbf{y}_1^T}{\partial X} \\ \vdots \\ \frac{\partial \mathbf{y}_m^T}{\partial X} \end{bmatrix} = \begin{bmatrix} \frac{\partial \mathbf{y}_1^T}{\partial \mathbf{x}_1} & \dots & \frac{\partial \mathbf{y}_1^T}{\partial \mathbf{x}_q} \\ \vdots & & \vdots \\ \frac{\partial \mathbf{y}_m^T}{\partial \mathbf{x}_1} & \dots & \frac{\partial \mathbf{y}_m^T}{\partial \mathbf{x}_q} \end{bmatrix}。$$

例 设 $\frac{\partial A}{\partial X} = \begin{bmatrix} 2xy & y^2 & y \\ x^2 & 2xy & x \end{bmatrix}$, $X = \begin{bmatrix} x \\ y \end{bmatrix}$, 根据 (12) 矩阵对列向量求导

法则, 有

$$\frac{\partial^2 A}{\partial X^2} = \begin{bmatrix} \frac{\partial(2xy)}{\partial X} & \frac{\partial(y^2)}{\partial X} & \frac{\partial y}{\partial X} \\ \frac{\partial(x^2)}{\partial X} & \frac{\partial(2xy)}{\partial X} & \frac{\partial x}{\partial X} \end{bmatrix} = \begin{bmatrix} 2y & 0 & 0 \\ 2x & 2y & 1 \\ 2x & 2y & 1 \\ 0 & 2x & 0 \end{bmatrix}。$$

例 设 $Y = \begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix}$, $X = \begin{bmatrix} u & x \\ v & y \\ w & z \end{bmatrix}$, 根据 (15) 矩阵对矩阵求导法则, 有

$$\frac{\partial Y}{\partial X} = \begin{bmatrix} \frac{\partial[a \ b \ c]}{\partial \begin{bmatrix} u \\ v \\ w \end{bmatrix}} & \frac{\partial[a \ b \ c]}{\partial \begin{bmatrix} x \\ y \\ z \end{bmatrix}} \\ \frac{\partial[d \ e \ f]}{\partial \begin{bmatrix} u \\ v \\ w \end{bmatrix}} & \frac{\partial[d \ e \ f]}{\partial \begin{bmatrix} x \\ y \\ z \end{bmatrix}} \end{bmatrix} = \begin{bmatrix} \frac{\partial a}{\partial u} & \frac{\partial b}{\partial u} & \frac{\partial c}{\partial u} & \frac{\partial a}{\partial x} & \frac{\partial b}{\partial x} & \frac{\partial c}{\partial x} \\ \frac{\partial a}{\partial v} & \frac{\partial b}{\partial v} & \frac{\partial c}{\partial v} & \frac{\partial a}{\partial y} & \frac{\partial b}{\partial y} & \frac{\partial c}{\partial y} \\ \frac{\partial a}{\partial w} & \frac{\partial b}{\partial w} & \frac{\partial c}{\partial w} & \frac{\partial a}{\partial z} & \frac{\partial b}{\partial z} & \frac{\partial c}{\partial z} \\ \frac{\partial d}{\partial u} & \frac{\partial e}{\partial u} & \frac{\partial f}{\partial u} & \frac{\partial d}{\partial x} & \frac{\partial e}{\partial x} & \frac{\partial f}{\partial x} \\ \frac{\partial d}{\partial v} & \frac{\partial e}{\partial v} & \frac{\partial f}{\partial v} & \frac{\partial d}{\partial y} & \frac{\partial e}{\partial y} & \frac{\partial f}{\partial y} \\ \frac{\partial d}{\partial w} & \frac{\partial e}{\partial w} & \frac{\partial f}{\partial w} & \frac{\partial d}{\partial z} & \frac{\partial e}{\partial z} & \frac{\partial f}{\partial z} \end{bmatrix}。$$